Stochastic Search and Neural Networks

Natural language and ARtificial intelligence Group



Problem Spaces

- Feature is a single point of data
- Feature vector is a collection of points of data (all relating to different things)
- Problem space is the space that spans all possible combinations of features



Problem Space Example

- We have height, weight, eye color and gender
- Each item in the list above is a feature
- A sample feature vector would be: [6'3", 140lbs, blue, male]
- Problem space is the combination of all feature vectors (all heights, eye colors, etc.)

* *

Fitness Landscape

- Also known as "Error Spaces"
- Adds error vector/point to the problem space
- Fitness landscape is the set of all feature vectors **and** error vectors



Fitness Landscape Example

- Last time out PSO was looking for the vector [5, 8] in the set of all real numbers
- Time to show the problem space and the fitness landscape



Optimization Problems

- Al can be defined as an optimization where the user want's to minimize error
- Two main types stochastic and gradient search
 - Gradient follows the shape of the fitness landscape
 - Stochastic wanders throughout the problem space



Grapher Time





Problem Space Search





Fitness Landscape Search





PSO Overview

- Initialize the particles
 - Set starting location, velocity and fitness
- While stop criteria hasn't been met
 - Check each particles fitness saving the best ever and the best at this time
 - Flock particles toward the best at this time and the best ever



PSO Runtime

```
function run_pso (param, fitness_func)
```

```
local particles = init_particles(num, dim, random)
```

```
local pbest = particles[1]
local gbest = particles[1]
```

```
while iterations > 0 and pbest.f > success do
    pbest, gbest = calc_fitness(particles, fitness_func, pbest)
    update_particles(particles, pbest, gbest, pphi, gphi)
    print_particles(particles)
    iterations = iterations - 1
end
```

return pbest

end



PSO Updates

```
function update_position (particle)
    local position = {}
    for i=1, getn(particle.p) do
        tinsert(position, particle.p[i] + particle.v[i])
    end
    return position
end
function update velocity (particle, pbest, gbest, pphi, gphi)
   local velocity = {}
    for i=1, getn(particle.v) do
        local prand = pphi*random()
        local grand = gphi*random()
        local pdiff = pbest.p[i] - particle.p[i]
        local gdiff = gbest.p[i] - particle.p[i]
        local vel = particle.v[i] + (prand * pdiff) + (grand * gdiff)
        tinsert(velocity, vel)
    end
    return velocity
end
```







- Networks of perceptrons or nodes
- Known for pattern matching abilities
- Applied to a wide variety of problems
- Eventually taken over by Kernel Methods
- Originally developed in the 40's



- Category of AI techniques
- Describes a data structure more than an algorithm
- Can be trained in a number of ways:
 - Particle Swarm Optimizers
 - Backpropagation
 - Genetic Algorithms



- Consist of a couple of directed graphs
 - A graph describing the topology (with or without cycles)
 - A graph describing the weights
- And a couple of arrays
 - Node outputs
 - Inputs from problem



```
{
     topology = {
           \{0,0,0,1,1,0,0,0,0\},\
           \{0,0,0,1,1,0,0,0,0\},\
           \{0,0,0,1,1,0,0,0,0\},\
           \{0,0,0,0,0,1,1,1,1\},\
           \{0,0,0,0,0,1,1,1,1\},\
           \{0,0,0,0,0,0,0,0,0,0\},\
           \{0,0,0,0,0,0,0,0,0,0\},\
           \{0,0,0,0,0,0,0,0,0,0\},\
           \{0,0,0,0,0,0,0,0,0,0\},\
     },
     weights = {
           {-71.74.-115.30.160.06.-545.12.-609.04.226.24.-123.90.-44.55.59.67},
           {-28.71,56.79,4.64,-241.84,36.33,2.90,22.42,963.65,-243.77},
           {34.48, -23.07, 18.73, 5.06, -49.50, 20.98, -672.58, -32.82, -210.05},
           {204.72,126.70,68.57,95.91,232.92,290.05,-47.89,-33.47,-243.83},
           {97.01,27.22,-10.15,-40.74,77.39,-1.12,50.06,-36.96,-36.25},
           {99.34,19.34,-49.66,207.24,-27.07,-68.55,-88.64,67.78,-60.34},
           {-49.95,88.91,174.00,17.13,179.01,-24.76,-62.09,51.42,-642.90},
           {161.85, -38.85, 13.80, -111.31, 88.18, 106.61, 77.94, -125.00, -18.63},
           {-38.83,41.05,126.66,81.32,-13.21,330.66,157.38,-58.26,232.19},
     },
     inputs = 3,
     outputs = 4,
     node_outputs = \{0, 0, 0, 0, 0, 0, 0, 0, 0, 0\}
}
```



NN Initialization

```
function init_neuralnet (topology, inputs, outputs)
    local neuralnet = {}
    neuralnet.topology = topology
    neuralnet.weights = init_weights(getn(topology))
    neuralnet.inputs = inputs
    neuralnet.outputs = outputs
    neuralnet.node_outputs = init_node_outputs(getn(topology))
    return neuralnet
end
```

```
function init_node_outputs(nodes)
    local outputs = {}
    for i=1, nodes do
        tinsert(outputs, 0)
    end
    return outputs
end
```

end

```
function init_weights(nodes)
    local weights = {}
    for i=1, nodes do
        local row = {}
        for j=1, nodes do
            tinsert(row, 1)
        end
        tinsert(weights, row)
    end
    return weights
end
```



NN Run (Chunk I)

```
function run_net(net, inputs)
    -- set the proper inputs in the node outputs.
    -- i.e. artificially fire the input nodes based
    -- on input given.
    for i=1, getn(inputs) do
        if inputs[i] == 1 then
            net.node_outputs[i] = 1
        else
            net.node_outputs[i] = 0
        end
    end
```



NN Run (Chunk 2)

```
-- Fire all the nodes (in a naive feed forward fashion)
-- NOTE: Fix this later for recurrent neural networks.
-- NOTE: Naive means slow as balls.
for i=net.inputs+1, getn(net.topology) do
    local action_potential = 0
    for j=1, getn(net.topology) do
        if i ~= j then -- Beware there be hack-dragons in this code
            action_potential = action_potential +
                (net.topology[j][i] *
                net.weights[j][i] *
                net.node_outputs[j])
        end
    end
    if action_potential >= .95 then
        net.node outputs[i] = 1
    else
        net.node_outputs[i] = 0
    end
end
```



NN Run (Chunk 3)

```
-- Gather the outputs from the output nodes.
```

```
local output = {}
```

- -- For loops are clumsy in Lua, since there is no test statement
- -- and defaults to testing for equality I need to add the 1 to get
- -- the proper amount of outputs.

```
for i=getn(net.node_outputs), getn(net.node_outputs)-net.outputs+1, -1 do
    tinsert(output, net.node_outputs[i])
```

end

```
return output
end
```



PSO Neural Nets

- PSO's optimize some fitness function over a vector
- Lets make the fitness function construct a weight graph out of the particle's position vector and stuff it in a neural net
- Then we can run test cases on the net and see how bad it does



NN Training Task

• Given a binary number output 0-4 output a decimal number (or representation thereof)



Neural Net Topology





Fitness Function

- Create a Neural Net using weights defined by the current particle's position
- For each test case check the hamming distance from expected to actual
- Return the average hamming distance



Fitness Function (Chunk I)

function fitness_func (particle)
 local topology = {
 {0, 0, 0, 1, 1, 0, 0, 0, 0},
 {0, 0, 0, 1, 1, 0, 0, 0, 0},
 {0, 0, 0, 1, 1, 0, 0, 0, 0},
 {0, 0, 0, 0, 0, 1, 1, 0, 0},
 {0, 0, 0, 0, 0, 0, 1, 1, 1, 1},
 {0, 0, 0, 0, 0, 0, 0, 0, 0, 0},
 {0, 0, 0, 0, 0, 0, 0, 0, 0},
 {0, 0, 0, 0, 0, 0, 0, 0, 0},
 {0, 0, 0, 0, 0, 0, 0, 0, 0},
 {0, 0, 0, 0, 0, 0, 0, 0, 0},
 {0, 0, 0, 0, 0, 0, 0, 0, 0}

}



Fitness Function (Chunk 2)

```
local test_inputs = {
    {0, 0, 0},
    {0, 0, 1},
    {0, 1, 0},
    {0, 1, 1},
    {1, 0, 0},
}
local test_outputs = {
    {0, 0, 0, 0},
    {0, 0, 0, 1},
    {0, 0, 1, 0},
    {0, 1, 0, 0},
    {1, 0, 0, 0}
}
```



Fitness Function (Chunk 3)

local nn = make_net_from_pso(topology, particle)

```
local err = 0
for i=1, getn(test_inputs) do
    local output = run_net(nn, test_inputs[i])
    for j=1, getn(output) do
        if output[j] ~= test_outputs[i][j] then
            err = err + 1
            end
        end
        reset_outputs(nn)
end
return err/getn(test_inputs)
end
```



Lets see the code





Fitness over Iterations





Fitness over Less Time



Off The Cuff

- Supervised versus unsupervised learning
- Generalizability of results and some tricks
- Simulation versus the physical world
- Data versus smarts

